SHIMADEN SERVO CONTROLLER

series EM51

- Small Size 80 (H) × 50 (W) mm
- Easy Installation
- Plug-in Type



SPECIFICATIONS

Input: Feedback Resistance: Output: Output Rating / Contact Protection:

Sensitivity: Dead Band: Output Operation Display:

Operating Ambient Temperature Range: Operating Ambient Humidity: Power Supply: Power Consumption: Insulation Resistance:

Dielectric Strength:

External Dimensions: Installation. Weight: See ordering information. $100\Omega \sim 2k\Omega$ randam / 3-wire Relay contact or Triac (SSR) Relay contact = 240V AC, 1A (inductive load) / CR Absorber Triac (SSR) = 20~120V AC / (inductive load) / CR Absorber + varistor Approx. 0.5% fixed of input signal range 1~10% variable of input signal range

1~10% variable of input signal range M2-M1 / LED green lighting M2-M3 / LED red lighting

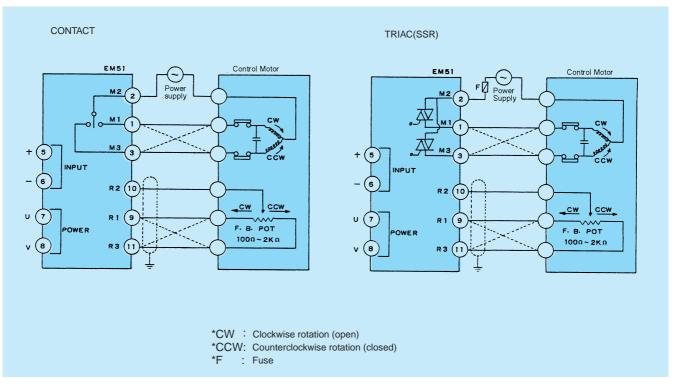
-10~+50 °C 90% RH max. See ordering information. Approx. 3V A 500V DC, 100M Ω between the input and power supply terminals 500V DC, 100M Ω between the output and power supply terminals 1 min. at 1000V AC between the output and power supply terminals

80 (H) \times 50 (W) \times 130 (D) mm 11P plug-in Approx. 350g

ORDERING INFORMATION

ITEM	CODE					SPECIFICATIONS
SERIES	EM51-					Plug-In Type Servo Controller
		1			1~5mA DC, Receiving resistance: 250Ω	
CONTROL INPUT			2			4~20mA DC, Receiving resistance: 62Ω
		3	3			0~10V DC, Input resistance: 200kΩ
		9	9			Others (Please consult before ordering.)
OUTPUT			Y			Contact 240V AC, 1A (inductive load)
			6	s		Triac 20~120V AC, 1A (inductive load)
			5			(Motor Supply Voltage: 20~120V AC)
POWER SUPPLY				13-		100~110V AC ± 10%, 50 / 60Hz
			14- 15- 16-			110~120V AC ± 10%, 50 / 60Hz
						200~220V AC ± 10%, 50 / 60Hz
						220~240V AC ± 10%, 50 / 60Hz
				99-		Others (Please consult before ordering.)
REMARKS				0	Without	
				9	With (Please consult before ordering.)	

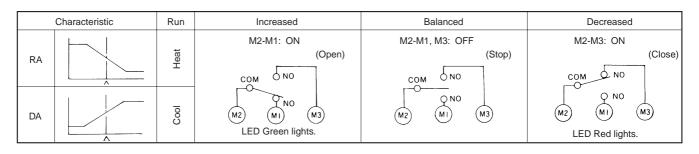
CONNECTION DIAGRAM



* When reversing the motor rotation, convert the terminal connections M1-M3 and R1-R3 as per the dotted lines.

- * For model with Triac (SSR), motor power supply voltage range must be 20~120V AC.
- * Recommend to use fuse between terminal M2 and power supply terminals to protect motor when malfunctioned.

RELAY ACTIONS



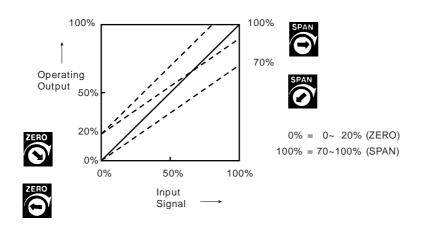
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INSTALLATIONS

- * Free from corrosive gasses.
- * Away from direct sunlight, impact and radiant heat from electric ovens or other heat equipment.

ADJUSTMENT

1. Characteirstics of Input Signal vs.Operating Output



2. Adjustment of Operating Output

Confirm that the final control element is at 100% or the open position when 100% input signal is applied, and at 0% or the closed position when 0% input signal is applied.

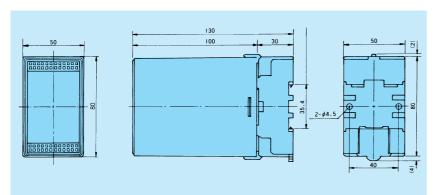
If there is any dislocation at the 100% and / or 0% position, adjust the ZERO and SPAN trimmers accordingly.

Note: Since the reaction of the final control element is normally slow, adjust the ZERO and SPAN trimmers slowly.

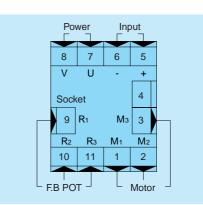
3. Adjustment of Deadband

The dead band means the sensitivity between the clockwise (open) and counterclockwise (close) actions of the control motor. If the control motor repeats quick hunting, turn the dead band from the narrow band gradually to the wide band until hunting stops. ff the dead band is set unnecessarily wide, the control motor may be dull in response.





TERMINAL ARRANGEMENT



A Warning

• This product is designed for the control of temperature, humidity and other physical values for the general industrial equipment. It is not to be used for any purpose which regulates the prevention of serious effects on human life or safety. No warranty, express or implied is valid if used without proper safety measures.

Caution

• If the possibility of loss or damage to your system or property as a result of failure of any part of the process exists, proper safety measures must be made before the instrument is put into use as to prevent the occurrence of trouble.

